### HGM の不安定性をどう回避するか? 高山信毅 (神戸大)

### HGM の三つの step

- 1. パラメータ付定積分のみたす線形偏微分方程式系を代数的ア ルゴリズム等で見つける.
- 2. 初期条件を計算
- 3. 微分方程式の数値解析で,パラメータ付定積分の値を決める.

Step 3 がむつかしくなる場合の例,困難の回避の方法.

"Algorithms to Reduce the Instability of the HGM and Tricks Useful for the HGM", preprint (expository, technical).

1. このスライドの PDF: Nobuki Takayama [search] 2. http:

//www.math.kobe-u.ac.jp/OpenXM/Math/hgm/ref-hgm.html

復習: Runge-Kutta 法

$$\frac{dF}{dt} = P(t)F \tag{1}$$

where P(t) is an  $r \times r$  matrix and F(t) is a column vector valued unknown function. Let E be the  $r \times r$  identity matrix.

 $F_1 = F_0 + hk_1 = (E + hP(t_0))F_0, \quad k_1 = P(t_0)F_0.$  $F(t_0+h) - F_1 = F(t_0) + F'(t_0)h + O(h^2) - F_1 = O(h^2), \ F'(t_0) = P(t_0)F_0$ 

The 4th order Runge-Kutta (RK) method.

$$k_{i+1} = P(t_0 + c_{i+1}h)(F_0 + a_{i+1}k_ih), \quad k_0 = 0$$
 (2)

$$F_1 = F_0 + h(b_1k_1 + b_2k_2 + b_3k_3 + b_4k_4)$$
(3)

Determine the constants so that  $F_1 - F(t_0 + h) = O(h^5)$  where F(t) is the solution with the initial condition  $F(t_0) = F_0$ .  $a_1 = c_1 = 0$ ,  $b_1 = 1/6$ ,  $b_2 = 1/3$ ,  $b_3 = 1/3$ ,  $b_4 = 1/6$ ,  $c_2 = c_3 = c_4 = 1/2$ ,  $a_2 = a_3 = 1/2$ ,  $a_4 = 1$ . E.Hairer, S.P.Norsett, G.Wanner, Solving ordinary differential equations I, II, 1993, 1996, Springer

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 $\begin{aligned} Q(t,h) &= E + hP(t), & \text{for the first order RK} \\ \text{or } Q(t,h) \text{ is an analogous matrix for the 4th order RK. Then,} \\ F_{k+1} &= Q(k)F_k \; (Q(k) = Q(t_0 + kh, h) \text{ in short}). \text{ We call} \\ Q(k)Q(k-1)\cdots Q(1)Q(0) \end{aligned}$ 

the matrix factorial. Applying the matrix factorial to  $F_0$ , we obtain  $F_{k+1}$  (approximate solution).

Methods for exact evaluation of matrix factorials (the binary splitting and the modular method)\*. 以下おまけ話題.



 $5 \times 5$  contingency table, a benchmark test of evaluating the normalizing constant (*A*-hypergeometric polynomial) with 32 processes from [tgkt]. *N* is a parameter in the marginal sum.

\*[tgkt] Y.Tachibana, Y.Goto, T.Koyama, N.Takayama; Holonomic Gradient

### 復習: adaptive Runge-Kutta method

Let  $F_1$  be the vector determined by RK (of the 4th order) of the step size 2h (not h). Let  $F_2$  be the vector determined by RK two times with the step size h.

$$|F(t_0+2h)-F_1|=\phi(2h)^5+O(h^6)$$
(4)

where  $\phi$  depends only on the solution F and  $t_0$ . We also have

$$|F(t_0+2h)-F_2|=\phi h^5+\phi' h^5+O(h^6)$$
(5)

Assume  $\phi = \phi'$ . Taking the difference of (5) and (4), we have

$$|F_2 - F_1| \sim 30\phi h^5 + O(h^6)$$
 (6)

The good point of this identity is that we can estimate  $\phi$  without knowing the true solution F(t) and estimate the coefficient of the error. We put  $\Delta(h) = 30\phi h^5$ .

復習: adaptive Runge-Kutta method 続き

Let us assume

$$\Delta = \varepsilon |F_0| \tag{7}$$

Then,  $\phi = |F_0|\varepsilon/(30h^5)$ . Then the relative error  $|(F(t + h_0) - F_1)/F_0|$  is bounded by

$$\frac{|\phi|h^5}{|F_0|} + O(h^6) = \frac{\varepsilon}{30} + O(h^6)$$
(8)

When we want to make the relative error smaller than  $\frac{\varepsilon}{30}$ , we need to make  $\Delta(h)$  (difference of 2h step and two times of h step) smaller than  $\varepsilon |F_0|$ . In order to choose the next h, the product of r is the product of the step.

in order to choose the next

use the following relation

$$\frac{h_0}{h_1} = \left(\frac{\Delta(h_0)}{\Delta(h_1)}\right)^{1/5}$$

--> load("ak2.rr");

- --> QQ=rk\_mat2(newmat(2,2,[[0,1],[t,0]])
- --> base\_replace(QQ[0],QQ[1]);

[ 1/6\*h^3\*t^2+(1/6\*h^4+h)\*t+1/24\*h^5+1/2

小話: 複素領域で ODE を数値解析 (とばす)

$$rac{d}{dz}F=P(z)F,\quad z\in{f C}$$

We want to solve the differential equation along the path

$$z = z_0 + (z_1 - z_0)t, \quad 0 \le t \le 1, z_0, z_1 \in \mathbf{C}$$

with the initial value  $F(z_0) = F_0$ . By  $d/dz = (z_1 - z_0)^{-1} d/dt$ ,

$$\frac{dF}{dt} = (z_1 - z_0)P(z_0 + (z_1 - z_0)t)F$$
(9)

Decompose  $(z_1 - z_0)P(z_0 + (z_1 - z_0)t)$  into the real part and the imaginary part as  $P_1(t) + \sqrt{-1}P_2(t)$  Put  $F = u + \sqrt{-1}v$ .

$$\frac{d}{dt} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} P_1 & -P_2 \\ P_2 & P_1 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}$$
(10)

c2rsys(P(t));

Defusing method (heuristic) 1

$$\frac{dF}{dt} = P(t)F$$
(11)  

$$F(t_0) = F_0^{\text{true}} \in \mathbf{R}^n$$
(12)

 $F_0^{\text{true}}$  is the initial value of F at  $t = t_0$ . Situation

F

- 1. The initial value has at most 3 digits of accuracy. We denote this initial value  $F_0$ .
- 2. The property  $|F| \to 0$  when  $t \to +\infty$  is known, e.g., from a background of the statistics.
- 3. There exists a solution  $\tilde{F}$  of (11) such that  $|\tilde{F}| \gg 0$ ,  $t \to +\infty$ .

Under this situation, the HGM works only for a very short interval of t because the error of the initial value vector makes the fake solution  $\tilde{F}$  dominant and it hides the true solution F(t). We call this bad behavior of the HGM *the instability of the* HGM.

Defusing method 2. 例.

## Example

$$\frac{d}{dt}F = \left(\begin{array}{rrr} -1 & 1 & 0\\ 0 & -1 & 1\\ 0 & 0 & 0 \end{array}\right)F$$

The solution space is spanned by $F^1 = (\exp(-t), 0, 0)^T$ ,						
$F^2 = (0, \exp(-t), 0)^T, F^3 = (1, 1, 1)^T$ . The initial value						
$(1,0,0)^T$ at $t = 0$ yields the solution $F^1$ . Add some errors						
$(1, 10^{-30}, 10^{-30})^T$ to the initial value. Then, we have						
t	value ${\cal F}_1$ by RK	difference $F_1 - F^1$				
50	1.92827e-22	9.99959e-31				
60	8.75556e-27	1.00000e-30				
70	1.39737e-30	1.00000e-30				
80	1.00002e-30	1.00000e-30				
We can see the instability						

We can see the instability.

Defusing method 3. Airy function を以下の例に

From the Airy differential equation y''(t) - ty(t) = 0 by  $F = (y(t), y'(t))^T$ ,

$$P(t) = \begin{pmatrix} 0 & 1 \\ t & 0 \end{pmatrix}.$$
  
Ai(t) =  $\frac{1}{\pi} \lim_{b \to +\infty} \int_0^b \cos\left(\frac{s^3}{3} + ts\right) ds$ 

(Airy function) is a solution of the Airy differential equation. We want to obtain values of Ai(x) by RK.<sup>†</sup>



<sup>†</sup>More advanced method is "S.Chevillard, M.Mezzarobba, Multiple-precision evaluation of the Airy Ai function with reduced cancellation, @arxiv:1212.4731"

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Defusing method 4. Algorithm

$$F_{k+1} = Q(k)F_k. \ Q = Q(N-1)\cdots Q(1)Q(0).$$

## Algorithm

- 1. Obtain eigenvalues  $\lambda_1 > \lambda_2 > \cdots > \lambda_r > 0$  (assumption) of Q and the corresponding eigenvectors  $v_1, \ldots, v_r$ .
- 2. Let  $\lambda_m$  be the eigenvalue which is almost equal to 0.
- 3. Express the initial value vector  $F_0$  containing errors in terms of  $v_i$ 's as

$$F_0 = f_1 v_1 + \dots + f_r v_r, \quad f_i \in \mathbf{R}$$
(13)

- 4. Choose a constant c such that  $F'_0 := c(f_m v_m + \cdots + f_r v_r)$ approximates  $F_0$ .
- 5. Determine  $F_N$  by  $F_N = QF'_0$  with the new initial value vector  $F'_0$ . 要するに Q の大きい固有値に対応する固有空間の分を 初期値から除く.

We call this algorithm the *defusing method*. This is a heuristic algorithm .

### Defusing method 5. Airy の例

## Example

 $t_0 = 0, h = 10^{-3}, N = 10 \times 10^3, 4$ -th order Runge-Kutta scheme. We have  $\lambda_1 = 9.708 \times 10^9$ ,  $v_1 = (-5.097, -159.919)^T$ and  $\lambda_2 = 3.247 \times 10^{-7}$ ,  $v_2 = (-5.097, 37.16)^T = (a, b)$ . Then, m = 2. We assume the 3 digits accuracy of the value Ai(0) as 0.355 and set  $F'_0 = (0.355, 0.355b/a)$ . Then, the obtained value  $F_{5000}$  at t = 5 is (0.00010808, -0.00024685) by the defusing method. We have the following accurate value by Mathematica In[1]:= N[AiryAi[5]]; Out[1]= 0.00010834 On the other hand, we appy the 4th order Runge-Kutta method with  $h = 10^{-3}$  for  $F_0 = (0.355, -0.259)^T$ , which has the accuracy of 3 digits. It gives the value at t = 5 as (-0.147395, -0.322215), which is a completely wrong value, and the value at t = 10 as (-102173, -320491), which is a blow-up solution.

Example: defusing method for  $H_n^k(x, y)$ , 1

$$H_n^k(x,y) = \int_0^x t^k e^{-t} {}_0F_1(;n;yt) \mathrm{d}t.$$

## Proposition (dots)

The function  $u = H_n^k(x, y)$  satisfies

$$\{\theta_y(\theta_y + n - 1) + y(\theta_x - \theta_y - k - 1)\} \bullet u = 0, \\ (\theta_x - \theta_y - k - 1 + x)\theta_x \bullet u = 0.$$

where  $\theta_x = x \frac{\partial}{\partial x}, \theta_y = y \frac{\partial}{\partial y}$ . The holonomic rank of this system is 4. The ODE of y direction is unstable for  $H_n^k$ .<sup>‡</sup>

<sup>‡</sup>[dots] F.H.Danufane, K.Ohara, N.Takayama, C.Siriteanu, Holonomic Gradient Method-Based CDF Evaluation for the Largest Eigenvalue of a Complex Noncentral Wishart Matrix, https://arxiv.org/abs/1707.02564. 余談: *H*<sup>k</sup><sub>n</sub>(x, y) はどう応用される?

### Theorem (Kang-Alouini<sup>§</sup>)

When the matrix  $\Sigma^{-1}MM^{*\P}$  has the positive eigenvalues  $0 < \lambda_1 < \lambda_2 < \cdots < \lambda_s$ , then the cummulative distribution function of the largest eigenvalue  $\phi_s$  of S for the threshold x is

$$\mathrm{P}\left(\phi_{s}\leq x
ight)=rac{\exp(-\sum_{i=1}^{s}\lambda_{i})}{\Gamma(t-s+1)^{s}\prod_{1\leq i< j\leq s}(\lambda_{j}-\lambda_{i})}\det\Psi(x)$$

where  $\Psi(x)$  is a matrix valued function of which (i, j) element is

$$H_{t-s+1}^{t-i}(x,\lambda_j) = \int_0^x y^{t-i} \exp(-y) \,_0 F_1(\,;t-s+1;y\lambda_j) \, dy$$

<sup>§</sup>M. Kang, M. S. Alouini, Largest Eigenvalue of Complex Wishart Matrices and Performance Analysis of MIMO MRC Systems, IEEE Journal on Selected Areas in Communications 21 (2003), 418–426.

<sup>¶</sup>channel matrix *H* is  $N_T \times N_R$  complex valued random matrix. The column vector *X* satisfies E[X] = M and the convariance is  $\Sigma_{-1}^{-1} \times S = \Sigma_{-1}^{-1} H H^*_{-1}$ 

## Defusing Method for $H_n^k$ , 2.

The ODE of y direction is unstable for  $H_n^k$ . By the DEtools [formal\_sol] function of Maple, we have

$$\begin{split} h_1 &= (xy)^{-1/2(1/2+n)} \exp(-2(xy)^{1/2})(1+O(1/y^{1/2})), \\ h_2 &= y^{-k-1}(1+O(1/y)), \\ h_3 &= (xy)^{-1/2(1/2+n)} \exp(2(xy)^{1/2})(1+O(1/y^{1/2})), \\ h_4 &= y^{1-n+k} \exp(y)(1+O(1/y)), \end{split}$$

when  $y \to +\infty$ . What is the asymptotic behavior of the function  $H_n^k(x, y)$  when x is fixed? We compare the value of  $h_4$  and the value by a numerical integration in Mathematica<sup>||</sup>.

	У	Ratio		
	1000	7.36595030875893e-452	Junhava	
	2000	2000 2.64621603289928e-881		
	3000	2.67723893601667e-1311		
$Patio = (H^{10}(1/2 v))/(v^{1-n+k} exp(v))$ which				

Ratio =  $(H_1^{10}(1/2, y))/(y^{1-n+k} \exp(y))$ , which suggests that  $H_n^k$  is expressed by  $h_1, h_2, h_3$  without the dominant component  $h_4$ .

<sup>II</sup> The method to evaluate hypergeometric functions in Mathematica is still a black box. It is not easy to give a numerical evaluator of hypergeometric functions which matches to Mathematica in all ranges of parameters and independent variables.





log  $H_1^{10}(1, y)$ . Exact value (by numerical integration) and the value by our defusing method agree. The adaptive Runge-Kutta method with the initial relative error  $10^{-20}$  (upper curve) does not agree with the exact value when y is larger than about 25.

The relative error of  $H_1^{10}(1, y)$  of our defusing method. The relative error is defined as  $(H_d - H)/H$  where  $H_d$  is the value by the defusing method and H is the exact value.

小技1. 例 χ' 分布, 1.

Koyama\*\* gave an integral formula of a generalization of  $\chi^2$  distribution motivated by the work of Marumo, Oaku, Takemura^{\dagger\dagger}

### Theorem (koyama2019)

The probability density function  $f(x) = \frac{d}{dx}P(\sum_{k=1}^{n} X_{k}^{r} < x)$  (X<sub>k</sub>'s are i.i.d random normal variables with  $m = 0, \sigma = 1, r \ge 3$ ) is expressed by the following integrals.

$$f(x) = \frac{1}{\pi} \frac{1}{2\pi^{n/2}} \int_0^\infty \exp(-xs) \operatorname{Im} \left[\varphi_3(s) \exp(\sqrt{-1}\pi/r) + \varphi_0(s)\right]^n ds, r \text{ odd}$$
  

$$f(x) = \frac{1}{\pi} \left(\frac{2}{\pi}\right)^{n/2} \int_0^\infty \exp(-xs) \operatorname{Im} \left[\varphi_3(s) \exp(\sqrt{-1}\pi/r)\right]^n ds, r \text{ even}$$
(14)

\*\*[koyama2019] T. Koyama, An integral formula for the powered sum of the independent, identically and normally distributed random variables, preprint. Old version is at arxiv https://arxiv.org/abs/1706.03989

<sup>††</sup>[mot2014] N.Marumo, T.Oaku, A.Takemura, Properties of powers of functions satisfying second-order linear differential equations with applications to statistics, arxiv:1405.4451

$$\varphi_3(s) = \int_0^\infty \exp(-st^r) \exp\left(-\frac{e^{2\pi\sqrt{-1}/r}}{2}t^2\right) dt \qquad (15)$$

for s > 0 and

$$\varphi_0(s) = \int_0^\infty \exp(-st^r - t^2/2)dt \tag{16}$$

We will evaluate the following integral when r = 4 as an example.

$$f(x) = \frac{1}{\pi} \left(\frac{2}{\pi}\right)^{n/2} \int_0^\infty \exp(-xs) \operatorname{Im} \left[\varphi_3(s) \exp(\sqrt{-1}\pi/r)\right]^n ds,$$

<ロト <回 > < E > < E > E の Q (\* 17/27 小技1. 例  $\chi'$  分布, 3.

It seems that it is not a good method to evaluate f(x) itself by the HGM, because the rank of the holonomic system for the integrand becomes very high when *n* increases [mot2014].

It will be a good method to generate a table of  $\varphi_3$  by the HGM and use a one dimensional numerical integration method to obtain the value of the PDF f(x). Note that the HGM is a good method to generate a table of values.

Trick: use HGM as a subprocedure of a numerical integration.



小技1. 例 χ<sup>r</sup> 分布, 4.

## Proposition

The cummulative distribution function (CDF)  $P(\sum_{i=1}^{n} X_i^r < y)$  is approximately expressed as

$$\int_{0}^{b} \frac{1 - \exp(-ys)}{s} \xi(s) ds + c_{\alpha} \frac{b^{-\alpha}}{\alpha} - c_{\alpha} y^{\alpha} \int_{by}^{\infty} e^{-t} t^{-\alpha - 1} dt \quad (17)$$

where b is a sufficiently large number,  $\alpha = n/r$ , and  $\xi(s)$  is given in (18) and (19).

$$\xi(s) = \frac{1}{\pi} \frac{1}{(2\pi)^{n/2}} \operatorname{Im} \left[\varphi_3(s) \exp(\sqrt{-1}\pi/r) + \varphi_0(s)\right]^n \quad r \text{ is } \mathfrak{(d8)}$$
  
$$\xi(s) = \frac{1}{\pi} \left(\frac{2}{\pi}\right)^{n/2} \operatorname{Im} \left[\varphi_3(s) \exp(\sqrt{-1}\pi/r)\right]^n \quad r \text{ is even} \quad (19)$$

 $c_{\alpha}$  is a constant (see the preprint as to the explicit value).



The CDF  $F_n(y)$  for  $y \in [0, 10]$ , r = 4, n = 1, 3, 5, 7, 9, 10 (from the top to the bottom).

The CDF  $F_n(y)$  for  $y \in [10, 210]$ , n = 10, 30, 50, 70, 90, 100. Note that n = 90, 100 cases (two lower curves) give wrong values because of numerical error of high powers n.

ところで 
$$\varphi_3$$
 の微分方程式, 1  
Put
$$f(x_1, x_2) = \int_{-\infty}^{\infty} \exp(x_1 z^2 + x_2 z^r) dz$$
(20)

#### Lemma

The function f satisfies the following A-hypergeometric system

$$(2\theta_1 + r\theta_2 + 1) \bullet f = 0 \tag{21}$$

$$(\partial_1^{r_1} - \partial_2) \bullet f = 0, \quad (r = 2r_1 \text{ is even})$$
(22)  
$$(\partial_1^r - \partial_2^2) \bullet f = 0, \quad (r \text{ is odd})$$
(23)

where  $\theta_i = x_i \partial_i = x_i \frac{\partial}{\partial x_i}$ .

ところで  $\varphi_3$  の微分方程式, 2

#### Lemma

Fix  $x_1$  to a number. The function  $f(x_1, x_2)$  annihilated by the following ordinary differential operator

$$\left(\frac{-r}{2}\right)^{r_1} \prod_{k=0}^{r_1-1} \left(\theta_2 + \frac{2k+1}{r}\right) - x_1^{r_1} \partial_2 \quad (r \text{ is even}) \quad (24)$$
$$\left(\frac{-r}{2}\right)^r \prod_{k=0}^{r-1} \left(\theta_2 + \frac{2k+1}{r}\right) - x_1^r \partial_2^2 \quad (r \text{ is odd}) \quad (25)$$

 $\varphi_3(s)=f\left(-\frac{e^{2\pi\sqrt{-1}/r}}{2},-s\right).$ 

# 小技,例 *E*[*χ*(*M<sub>x</sub>*)], 1.

The expected Euler characteristic for the largest eigenvalue of a real Wishart matrix is numerically evaluated for a small sized Wishart matrix by HGM \*. Let  $A = (a_{ij})$  be a real  $m \times n$  matrix valued random variable with the density

$$p(A)dA, \quad dA = \prod da_{ij}.$$

We assume that p(A) is smooth and  $n \ge m \ge 2$ . Define a manifold

$$M = \{hg^T \mid g \in S^{m-1}, h \in S \in S^{n-1}\} \simeq S^{m-1} \times S^{n-1} / \sim$$

where  $(h, g) \sim (-h, -g)$  and h and g are regarded as column vectors and  $hg^T$  is a rank 1  $m \times n$  matrix. Put

$$f(U) = \operatorname{tr}(UA) = g^T A h, \quad U \in M$$

and

$$M_x = \{hg^T \in M \mid f(U) = g^T A h \ge x\}$$

We are interested in  $E[\chi(M_x)]$ .

\*[euler2019] N.Takayama, L.Jiu, S.Kuriki, Y.Zhang, Computations of the Expected Euler Characteristic for the Largest Eigenvalue of a Real Wishart Matrix, arxiv:1903.10099 小技,例 *E*[*χ*(*M<sub>x</sub>*)], 2.

Assume m = n = 2 and  $p(\vec{A})$  is a Gaussian distribution

$$p(A)dA = \frac{1}{(2\pi)^{mn/2} \det(\Sigma)^{n/2}} \exp\left\{-\frac{1}{2} \operatorname{Tr} (A - M)^T \Sigma^{-1} (A - M)\right\} dA.$$

The mean is expressed by the variable  $M = (m_{ij})$ . We gave an integral representation of  $E(\chi(M_x))$  in [euler2019]. Moreover, we derived an ODE of rank 11 for (26) by the computer algebra package HolonomicFunctions.m (C.Koutchan).

$$E[\chi(M_{\star})] = \frac{1}{2\pi^{2}} \int_{x}^{\infty} d\sigma \int_{-\infty}^{\infty} db \int_{-\infty}^{\infty} ds \int_{-\infty}^{\infty} dt \frac{s_{1}s_{2}(\sigma^{2} - b^{2})}{(1 + s^{2})(1 + t^{2})} \exp\left\{-\frac{1}{2}\tilde{R}\right\} (26)$$

where  $\tilde{R}$  is a rational function in  $\sigma, b, s, t, s_1, s_2, m_{11}, m_{21}, m_{22}$ . More precisely, put

$$R = s_1 (b \sin \theta \sin \phi + \sigma \cos \theta \cos \phi - m_{11})^2 + s_2 (\sigma \sin \theta \cos \phi - b \cos \theta \sin \phi - m_{21})^2 + s_1 (\sigma \cos \theta \sin \phi - b \sin \theta \cos \phi)^2 + s_2 (b \cos \theta \cos \phi + \sigma \sin \theta \sin \phi - m_{22})^2,$$

replace  $\sin, \cos in R$  by

$$\sin \theta = \frac{2s}{1+s^2}, \quad \cos \theta = \frac{1-s^2}{1+s^2}, \quad \sin \phi = \frac{2t}{1+t^2}, \quad \cos \phi = \frac{1-t^2}{1+t^2}.$$

and we set this  $\tilde{R}$ . We want to evaluate it when  $m_{11} = 1$ ,  $m_{21} = 2$ ,  $m_{22} = 3$ (means) and  $s_1 = 10^3$ ,  $s_2 = 10^2$ , |小技, 例 *E*[χ(*M*<sub>x</sub>)], 3.] bigfloat, 冪級数を使うのを躊躇しない

Trick: Do not hesitate to use the bigfloat and powerseries. We use series solutions as a basis of interpolation or extrapolation.



The extrapolation function with powerseries of 20000 terms. Solid line is the extrapolation function, which diverges when x > 3.8633. Dots are values by simulations.

We use bigfloat of size 380 to determine series solutions. 計算のチャレンジと問題など 1.

## Computational Try

R.Vidunas and A.Takemura<sup>†</sup> derived a system of linear partial differential equations for the outage probability  $P(\phi_s \leq x)$ . Try to make a numerical analysis of this system with Gröbner basis, the defusing method, or the method to obtain a stabile system.

### Problem

Derive a good system of non-linear equations satisfied by  $\det \Psi(x)$ . The theory of holonomic quantum field and Hirota bilinear equations might help to solve this problem. If we can find such system, try a numerical analysis of it.

## Computational Try

Try the defusing method for  $H_n^k(x, y)$  up to  $y \sim 10^8$ , which lies in a range to apply to practical problems.

<sup>&</sup>lt;sup>†</sup>R.Vidunas, A.Takemura, Differential relations for the largest root distribution of complex non-central Wishart matrices, arxiv:1609.01799

## 計算のチャレンジと問題など 2.

# Computational Try

The defusing method for non-linear equation needs to compute a composition of non-linear functions instead of the matrix factorial. What is the size of a problem feasible by current computer algebra systems?

# Computational Try

Marumo, Oaku, Takemura gave a method to derive a linear ODE for  $\varphi^n$ . The function  $\varphi_3$  for r = 4 satisfies a 2nd order linear ODE. Try to make a numerical analysis of the system for  $\varphi_3^n$  with the defusing method, or the method to obtain a stabile system.

### Problem

Give a method for a high precision evalution of the hypergeometric function  $_{r}F_{1}$  and  $_{r}F_{0}$ . Refer, e.g., to the paper by S.Chevillard and M.Mezzarobba.

## Computational Try

Try to make a numerical analysis of the ODE of rank 11 for  $E[\chi(M_x)]$  with the defusing method, or the method to obtain a stabile system.